

QUAID-I-AZAM UNIVERSITY ISLAMABAD

PhD Admission Test, Fall 2020

Max Marks: **100**

SUBJECT: **MATHEMATICS**

Pass Marks: **70**

CATEGORY: **Applied Mathematics** Time Allowed: **50 Minute**

- (1) An ODE together with initial conditions is called
(a) Initial value problem (b) Boundary value problem
(c) Initial and boundary value problem (d) Non of the these
- (2) The solution of an ODE is represented by a
(a) Point (b) Curve (c) Plane (d) None of the these
- (3) The general solution of a second order ODE contains arbitrary constants
(a) 0 (b) 2 (c) 4 (d) 6
- (4) $x^2y'' + xy' + y = 0$ is the standard form of the
(a) Euler-Cauchy equation (b) Euler-Lagrange equation
(c) Euler-Poincare equation (d) Euler-Legendre equation
- (5) If y_1, y_2, \dots, y_n are linearly independent solutions of an n -th order ODE then Wronskian of these solution
(a) must be positive (b) must be negative
(c) must vanish (d) Non of these
- (6) A general solution of non-homogeneous ODE on the interval I is the sum of complementary solution and
(a) Particular integral (b) Singular integral
(c) Multiple integral (d) Gaussian integral
- (7) A quasilinear PDE: $Au_{xx} + 2Bu_{xy} + Cu_{yy} = F(x, y, u, u_x, u_y)$ is called hyperbolic if
(a) $AC - B^2 < 0$ (b) $AC - B^2 = 0$
(c) $AC - B^2 > 0$ (d) Non of these
- (8) The Heat equation is also known as equation
(a) Fusion (b) diffusion (c) effusion (d) Non of these

- (9) Mathematical modeling of vibration of rectangular membrane results in equation
(a) Heat (b) Wave (c) Poisson (d) Helmholtz
- (10) First boundary value problem for PDE's is also known as problem
(a) Neumann (b) Dirichlet (c) Robin (d) Non of these
- (11) A solution of $x = g(x)$ is called point of g
(a) Multiple (b) Singular (c) Non-singular (d) Fixed
- (12) Strictly diagonally dominant matrices are
(a) Singular (b) Non-singular (c) Plural (d) Non-plural
- (13) Newton Raphson method is convergent
(a) Linearly (b) Quadratically (c) Cubically (d) Non of these
- (14) Global error of fourth order Runge-Kutta method is
(a) $O(h)$ (b) $O(h^2)$ (c) $O(h^3)$ (d) $O(h^4)$
- (15) ADI is a method to solve system of PDE's. ADI stand for
(a) Alternating direction implicit (b) Advance difference integral
(c) Amplitude deviation inequality (d) Non of these
- (16) A vector of length +1 is called a vector
(a) Unit (b) Positive (c) Negative (d) Non of these
- (17) Inner product of two vectors gives maximum value when vectors are oriented in direction
(a) Same (b) Opposite (c) Perpendicular (d) Non of these
- (18) The resultant vector of the cross product of two vectors is to the plane containing these vectors
(a) Inclined (b) Parallel (c) Perpendicular (d) Non of these
- (19) Three vectors in \mathbb{R}^3 are if and only if their scalar triple product is not equal to zero
(a) Linearly dependent (b) Linearly independent
(c) Non-Linearly dependent (d) Nonlinearly independent
- (20) The direction of gradient vector to a given surface is to the surface
(a) Normal (b) Inclined (c) Parallel (d) Non of these

- (21) If Z is a complex number then \bar{Z} is its reflection in the axes
(a) Imaginary (b) Real (c) Conjugate (d) Non of these
- (22) If $f(z)$ is analytic in a simply connected domain D then the integral of $f(z)$ is of path in D
(a) Independent (b) Dependant (c) Length (d) Non of these
- (23) The derived series of a power series has the radius of convergence as the original series
(a) Double (b) Multiple (c) Equal (d) Non of these
- (24) Weiestrass M-test is used for
(a) Convergence (b) Uniform convergence
(c) Divergence (d) Non of these
- (25) The singularity of $f(z)$ at $z = z_0$ is called a
(a) Residue (b) Dipole (c) Pole (d) Tripole

Dr. Amjad Hussain (Focal Person for PhD Admission Test)